

Operating Systems Engineering

Lecture 6: Multitasking

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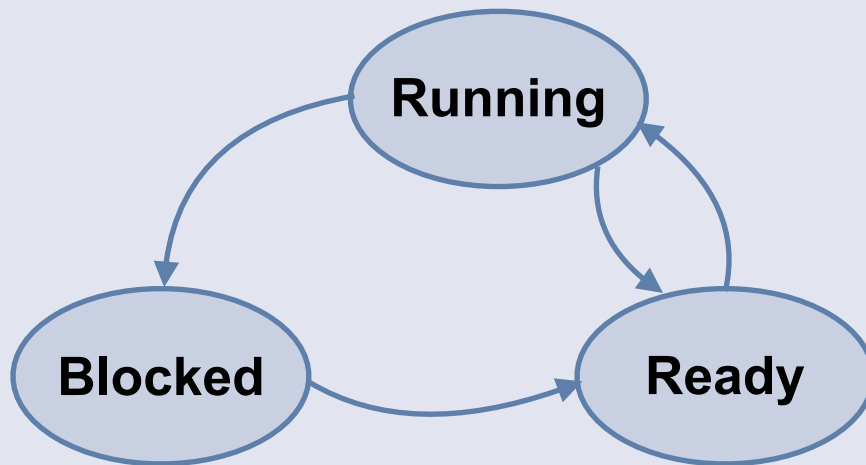
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- So far, we were quite imprecise when using the terms "program" (or "application") and "process"
- We can define both more precisely:
*A **process** is a **program in execution***
- A program is static, represented by the bytes of the executable file on a file system (or in our program header file arrays)
- A process has **state** that changes throughout its execution, e.g.:
 - The current program counter (instruction pointer)
 - The values of processor registers
 - The values of variables
 - In addition, information about resources, user IDs, permissions...
- All this state has to be **saved** when the process is not active (running)

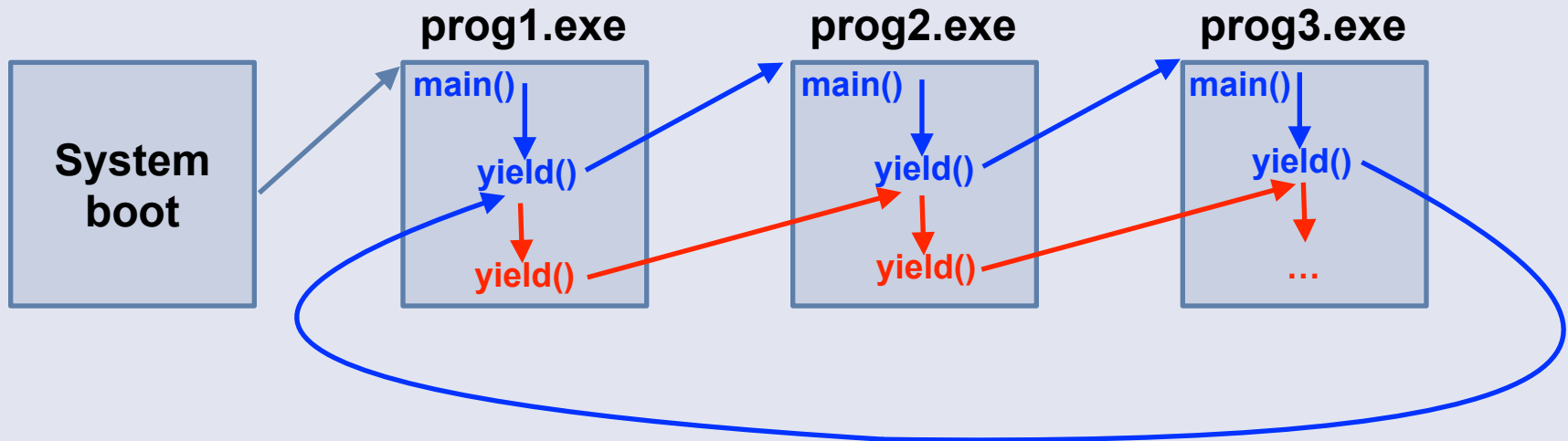
- In our current implementation, a process can either be **running** (it currently uses the processor) or **ready** (it has to wait until it is scheduled)
- In a more general process model, a process can also be **blocked**, i.e. waiting for the completion of an I/O operation it requested
- Each process transitions between these states:



Questions:

- How many processes can be in state "Running" at the same time on a single processor system?
- Why is there no transition from "Blocked" to "Running"?
- At which points in time do the transitions occur?
- What happens if all processes are blocked?

- Cooperative multitasking uses a `yield()` system call to switch between processes ***without terminating the calling process***
 - This requires more saving of state

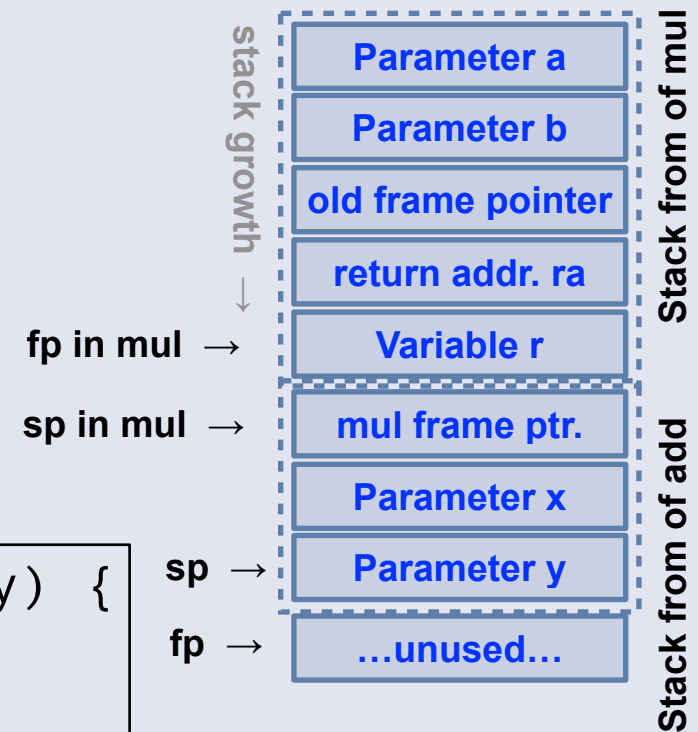


- A program calling `yield()` continues to execute after the call to `yield`
 - (almost) like a regular system call...

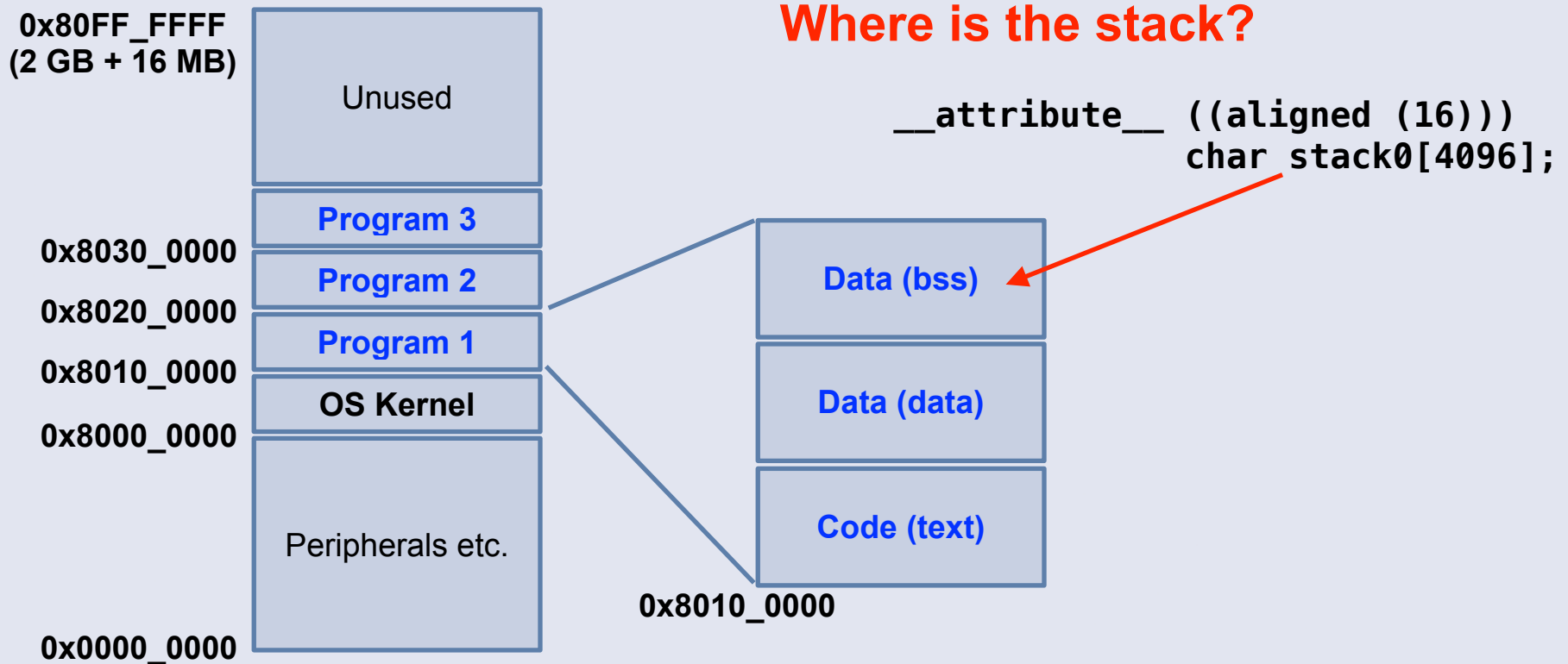
- The stack is used (by code generated by the compiler) to store the following *process state*:
 - local variables for each function in the call hierarchy
 - return addresses to a function higher up in the call hierarchy
- Example: function mul calls add
 - Add is a leaf function (calls no other function), does not require saving of the return address register r a

```
int mul(int a,b) {  
    int r = 0;  
    while (a--)  
        r = add(r,b);  
    return r;  
}
```

```
int add(int x,y) {  
    return x+y;  
}
```



- **All processes have to remain in memory now**
 - Code (text segments) is static and could be reloaded, but the data programs manipulate (data + bss segments) would need to be saved



- In our current setup, this still requires a separate linker script for each of the user processes
- **Idea:** parametrize the linker to dynamically define a start address for each of the processes (to $0x8000_0000 + 0x0010_0000 * \text{process ID}$) using a linker option on the gcc command line:

`-Wl,--defsym=PROC_START=$(VALUE_TO_OVERRIDE)`

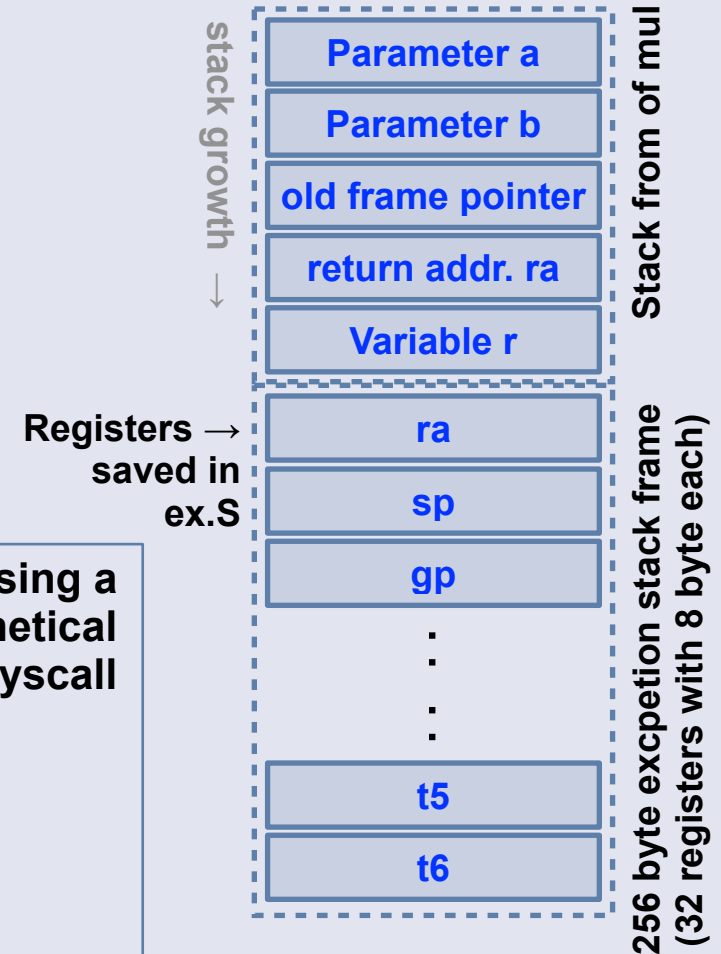
(see [4] for details)
- Virtual memory will make our life easier (later...)
 - All programs can be linked at the same address
 - The virtual memory subsystem uses the MMU to map the overlapping virtual address ranges of processes to separate virtual memory regions

What other data is important?

- *Register values* – we only have one set of registers for all processes
 - Executing another process (or the kernel code) overwrites values!
- We already have ex.S doing this
 - This already saves all registers to the process stack – even those saved by the exception C function prologue code

```
int mul(int a,b) {  
    int r = 0;  
    asm("mv a0, %0"::"r" (a));  
    asm("mv a1, %0"::"r" (b));  
    asm("li a7, 99");  
    asm("ecall");  
    asm("mv %0, a0":"=r" (r));  
    return r;  
}
```

**mul using a
hypothetical
mul syscall**



- Where does the OS store its own context?
 - In its own address range (0x8000_0000–0x800F_FFFF)
- Currently, there is not a lot of context to be saved:
 - `exception` only relies on
 - the `current_process` process ID (global variable in the data segment)
 - the `pcb` process control block array of `struct pcb_struct` (one entry per process), also in data
- What if we call other functions from `exception` that could return to user mode before they are finished, blocking I/O functions?
 - We would need a stack to store register values and the call hierarchy
 - This information could be stored on the current user process stack
 - Disadvantage: could be manipulated by a user process?
- **Idea:** provide a stack for the kernel and switch to/from it when entering/leaving M mode

- Simple implementation of a **round-robin scheduler**: the OS switches to a different process at every invocation of `yield()` – here shown for two processes
- The `pcb` struct holds the current **state** of the process
 - At the moment, we need the PC and SP at the point the exception was invoked (i.e. the `ecall` instruction in user mode)

```
case 23: // yield system call
        // save pc, stack pointer
        pcb[current_process].pc = pc;
        pcb[current_process].sp = s;

        // select new process
        current_process++;
        if (current_process > 2) current_process = 0;
        pc = pcb[current_process].pc; // add +4 later!

        break;
```

Simple scheduler saving
process context in
exception (kernel.c)

- Where can we get the values of the user process program counter **pc** and stack pointer from?
- The value of **pc** (address of the `ecall` instruction) was stored by the processor in when the exception was invoked
- The value of **s** needs to come from the assembler code in `ex.S`
 - Passed as parameter to our `exception` function
 - We can now use the values of `a0` and `a7` (parameter and system call number) stored on the stack frame in `ex.S`:

```
void exception(stackframe *s) {  
    uint64 pc, nr, param;  
  
    nr      = s->a7;    // read syscall number from stack  
    param   = s->a0;    // read parameter from stack  
  
    pc = r_mepc();    // read exception PC
```

**Read syscall nr, parameter
and exception PC value**

- The value of the user stack pointer **s** needs to come from the assembler code in `ex.S`
 - Passed as parameter to our `exception` function (in `a0`)
 - This is the stack pointer value after we saved all registers
- Now `a0` no longer contains the system call parameter!
 - Take this (and `a7`) from the user process stack as shown on the previous slide!

```
ex:                                     Stack handling  
                                     in ex.S  
    addi sp, sp, -256  
    sd ra, 0(sp)  
    ...  
    sd t6, 240(sp)  
  
    // set stackframe parameter  
    mv a0, sp  
  
    // call the C trap handler  
    call exception  
  
    // restore stackframe  
    mv sp, a1  
  
    // restore registers.  
    ld ra, 0(sp)  
    // ld sp, 8(sp)  
    ld gp, 16(sp)  
    ...  
    ld t6, 240(sp)  
    addi sp, sp, 256  
    mret
```

- Idea: Enable additional protection
 - So far: protect kernel from program accesses
 - Additional: **protect programs against each other**
- We now have to define PMP regions as follows in `setup.c`:
 - `0x0000_0000–0x7FFF_FFFF`: I/O
 - `0x8000_0000–0x800F_FFFF`: kernel
 - `0x80n0_0000–0x80nF_FFFF`: process `n`

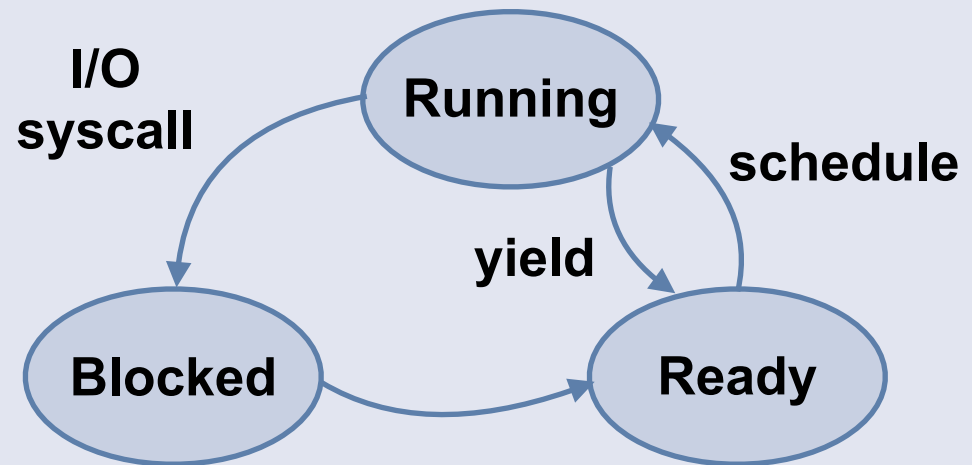
```
case 23: // yield system call
    // save pc, stack
    ...
    // Switch memory protection to new process
    if (current_process == 0)
        w_pmpcfg0(0x0f0000); // 2 - full access; 1,0 - no access
    else if (current_process == 1)
        w_pmpcfg0(0x0f000000); // 3 - full; 2,1,0 - no access
    // ...handle further processes in a more elegant way?
    break;
```

**Switching protection in the
exception handler (kernel.c)**

- Idea: Also enable switching at every system call
- This will enable us to implement our three-state process model
 - Running, Ready, Blocked
 - Switch from Running to Blocked when an I/O syscall is made
- This also enables *event loops* for interactive applications (see next slide)

Question:

- What happens in our process state diagram if a process calls syscall #42 (exit)?



- Event loops allow the OS to take back control **often**
 - ...but not always
 - relies on programmer discipline (and bug-free programs...)

```
PROCEDURE MyEventLoop;
```

```
VAR
```

```
    cursorRgn:      RgnHandle;
```

```
    gotEvent:       Boolean;
```

```
    event:          EventRecord;
```

```
BEGIN
```

```
    cursorRgn := NewRgn; {pass an empty region the first time thru}
```

```
    REPEAT
```

```
        gotEvent := WaitNextEvent(everyEvent, event, MyGetSleep,  
                                cursorRgn);
```

```
        IF (event.what <> kHighLevelEvent) AND (NOT gInBackground)  
            THEN MyAdjustCursor(event.where, cursorRgn);
```

```
        IF gotEvent THEN {the event isn't a null event, }  
            DoEvent(event) { so handle it}
```

```
        ELSE {no event (other than null) to handle }  
            DoIdle(event); { right now, so do idle processing}
```

```
    UNTIL gDone; {loop until user quits}
```

```
END;
```

**Example event loop application
code for Mac System 7**

1. Andrew Waterman, Krste Asanovic and John Hauser, *The RISC-V Instruction Set Manual Volume II: Privileged Architecture Document*, Version 20211203
2. SiFive Interrupt Cookbook,
<https://starfivetech.com/uploads/sifive-interrupt-cookbook-v1p2.pdf>
3. Free Software Foundation, *Debugging with gdb*, 10th Edition, section 10.19
https://sourceware.org/gdb/onlinedocs/gdb/Dump_002fRestore-Files.html
4. StackOverflow, *GNU LD: How to override a symbol value*,
<https://stackoverflow.com/questions/10032598/gnu-ld-how-to-override-a-symbol-value-an-address-defined-by-the-linker-script>